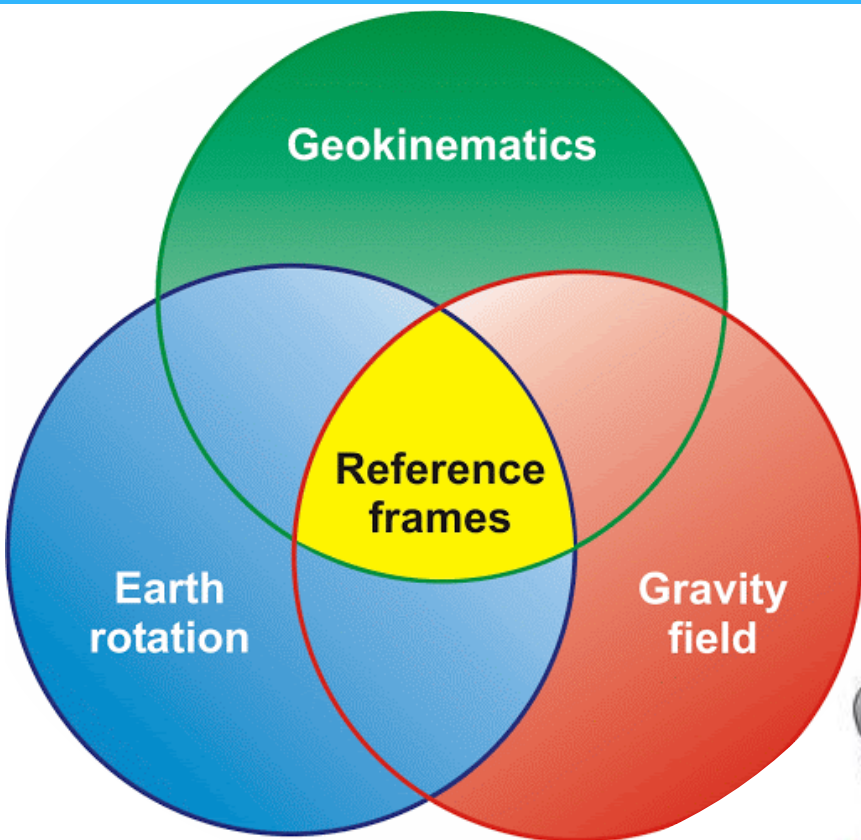
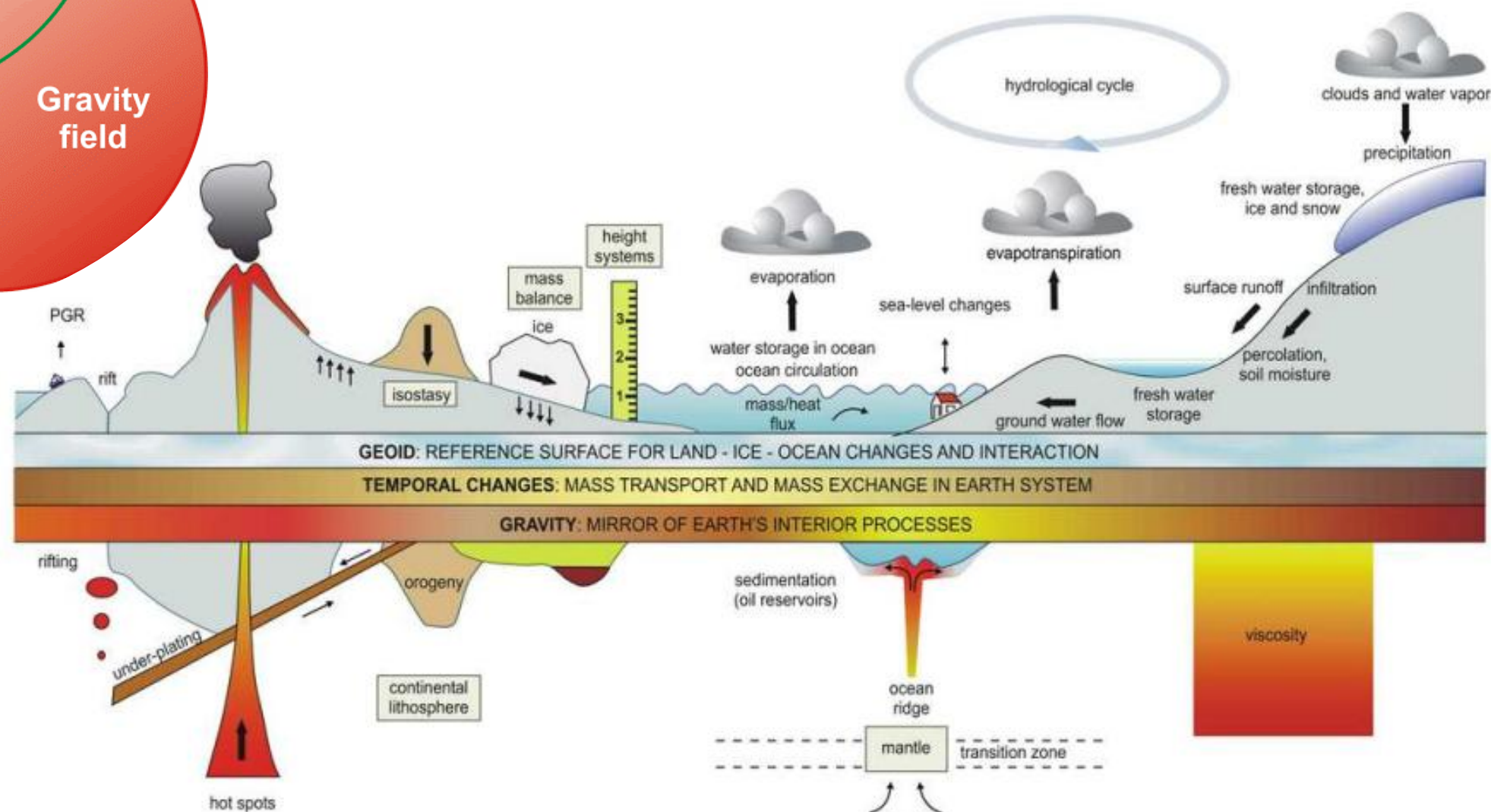


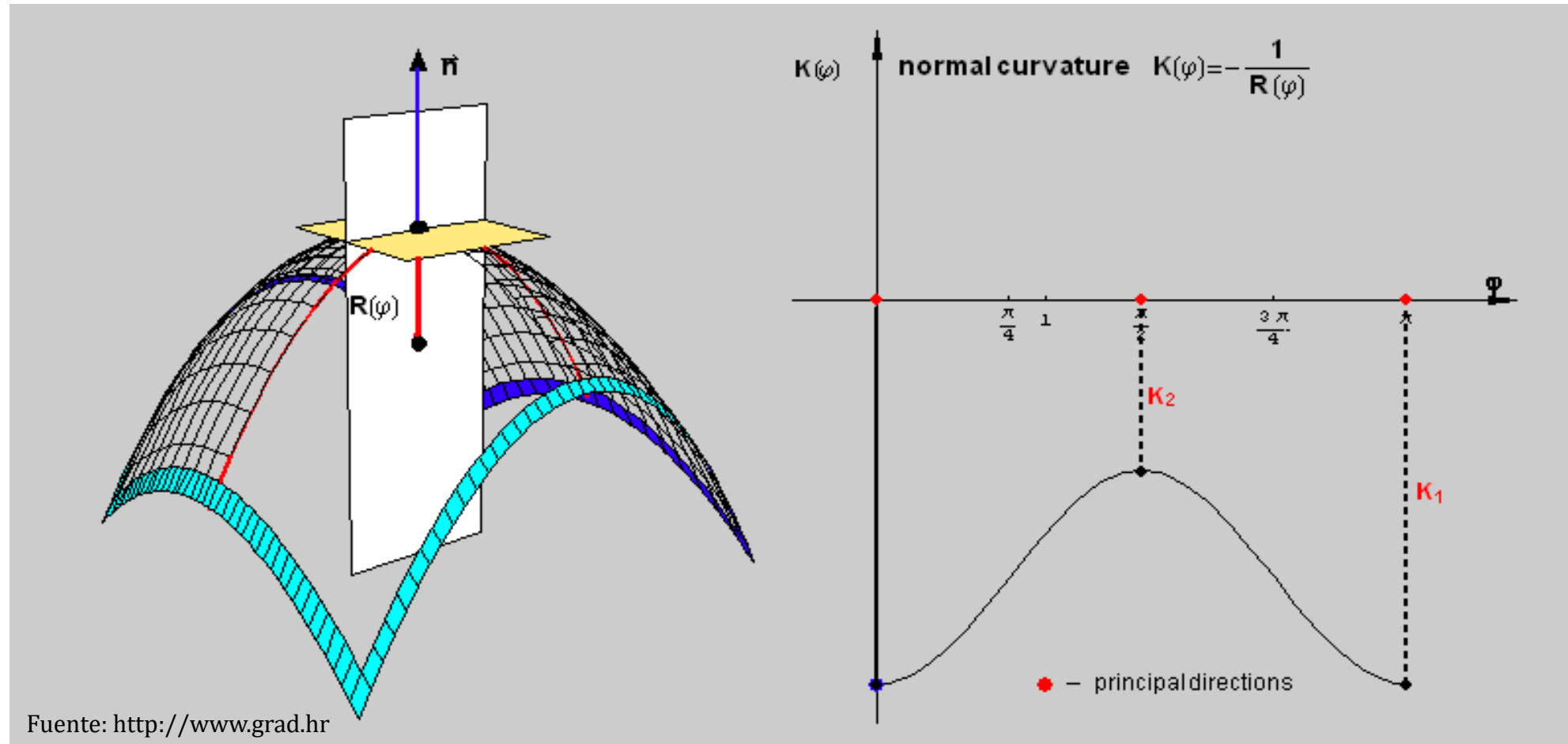


GEODESIA



Geodesia

Curvatura y Radio de Curvatura (6,7,9):



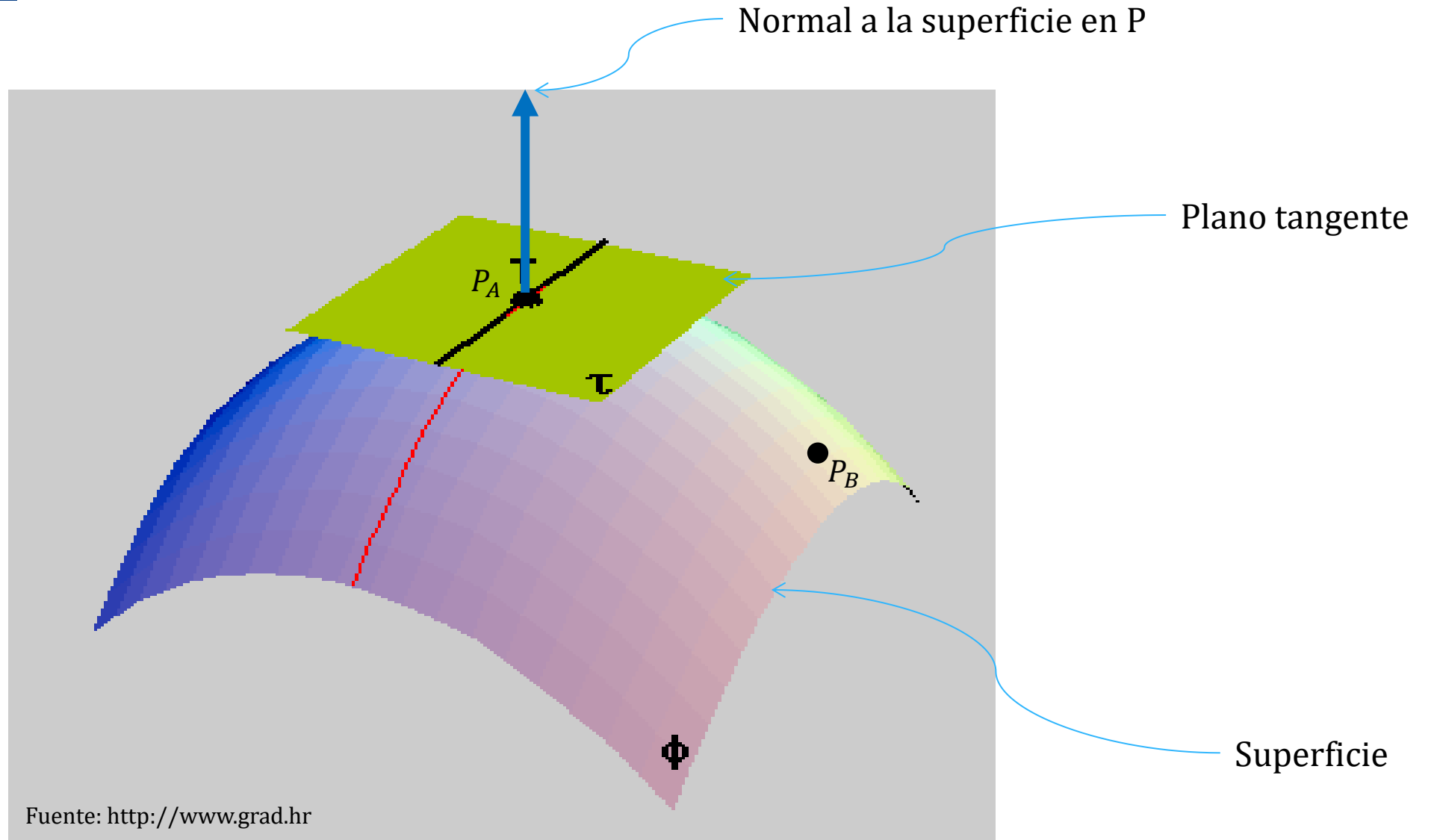
(6) Krakiwsky, Edward J., and Donald B. Thomson (1974). *Geodetic position computations*. Department of Surveying Engineering, University of New Brunswick.

(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences, Ohio State University.

Geodesia

Curvas^(6,7,9):



Curva de sección normal: es una curva plana creada por la intersección de un plano que contiene la normal a la superficie (un plano de sección normal) con la superficie.

(6) Krakiwsky, Edward J., and Donald B. Thomson (1974). *Geodetic position computations*. Department of Surveying Engineering, University of New Brunswick.

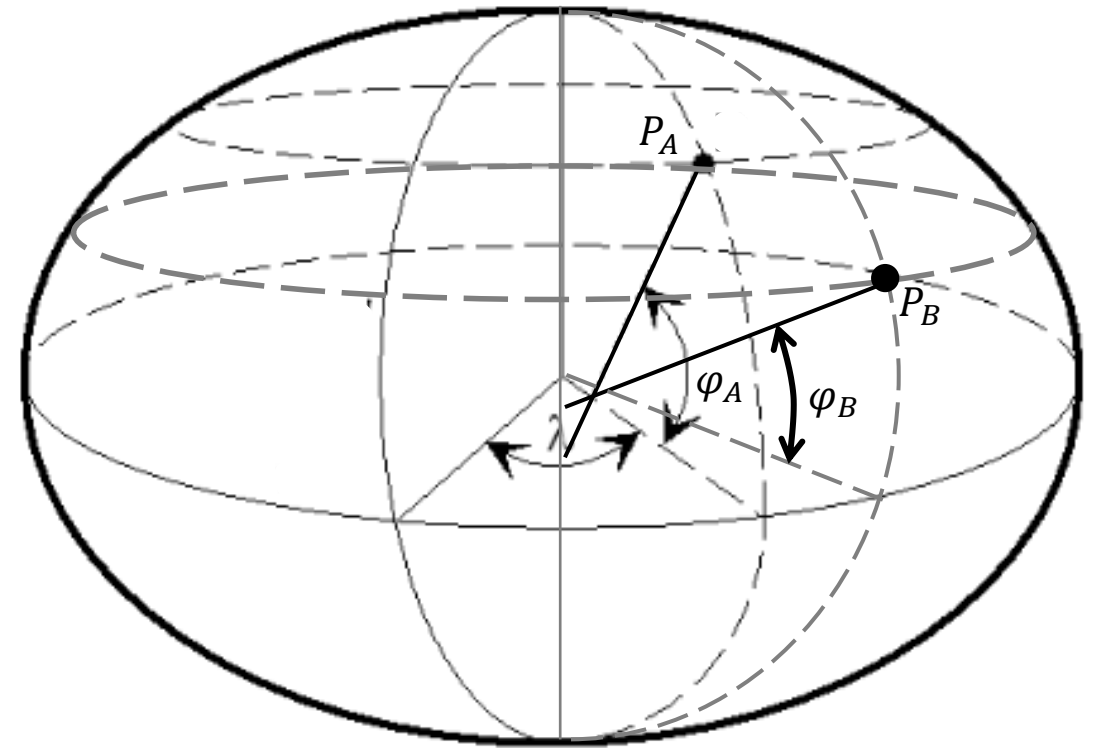
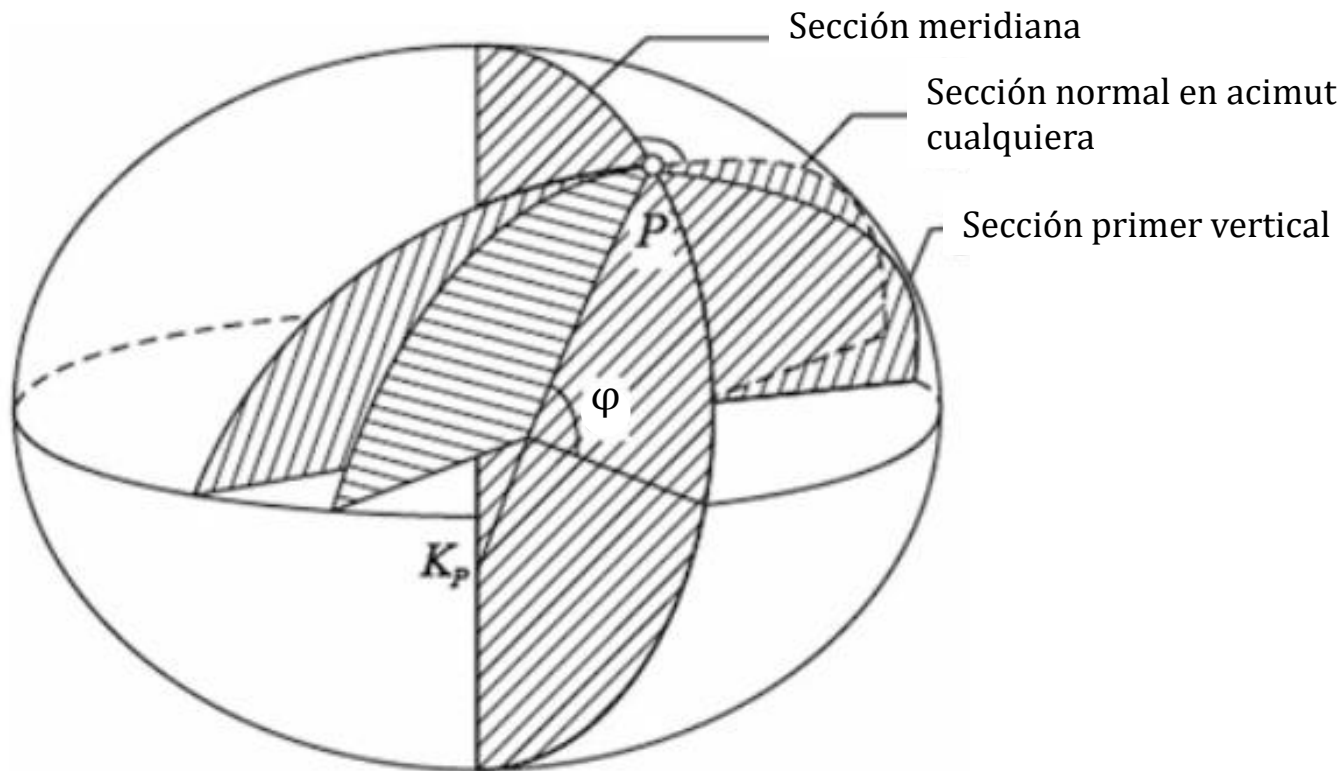
(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences, Ohio State University.

Geodesia

Secciones en el elipsoide^(7,9,10):

Sección Normal (definición matemática): curva formada por la intersección de un plano que contiene a la normal a la superficie del elipsoide en un punto dado.



Fuente: Lu Z., Qu Y., Qiao S. (2014)

(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

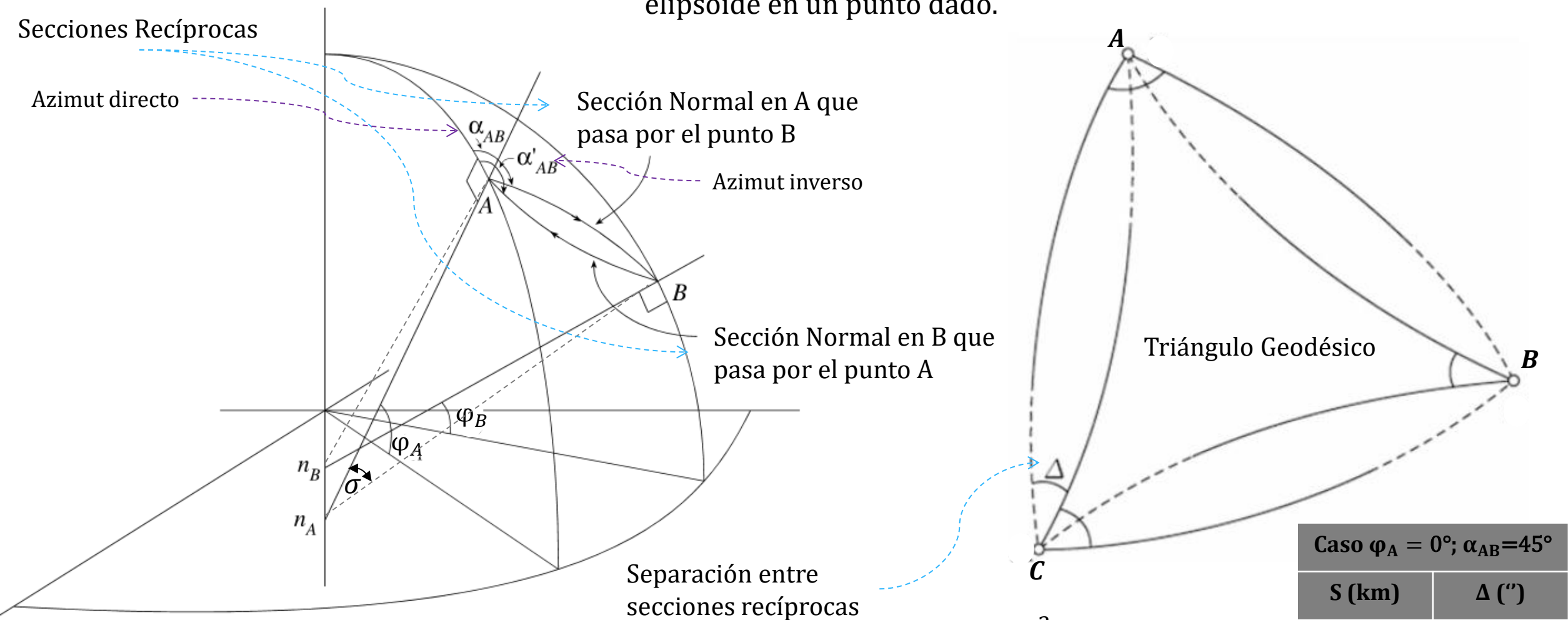
(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.

(10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service

Geodesia

Secciones en el elipsoide^(7,9,10):

Sección Normal (definición matemática): curva formada por la intersección de un plano que contiene a la normal a la superficie del elipsoide en un punto dado.



Fuente: Jekeli, C. (2006)

$$\Delta = \alpha_{AB} - \alpha'_{AB} = \frac{e^2}{4} \left(\frac{S_{AB}}{N_A} \right)^2 \sin 2\alpha_{AB} \cos^2 \varphi_m$$

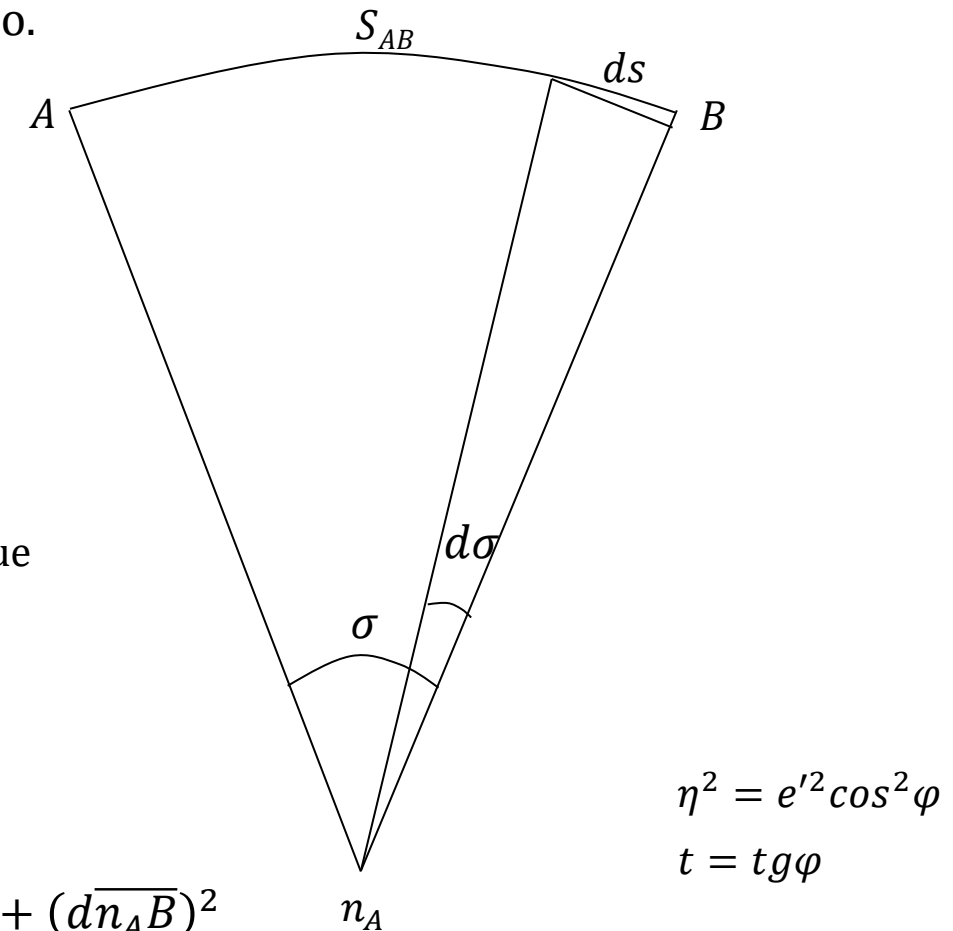
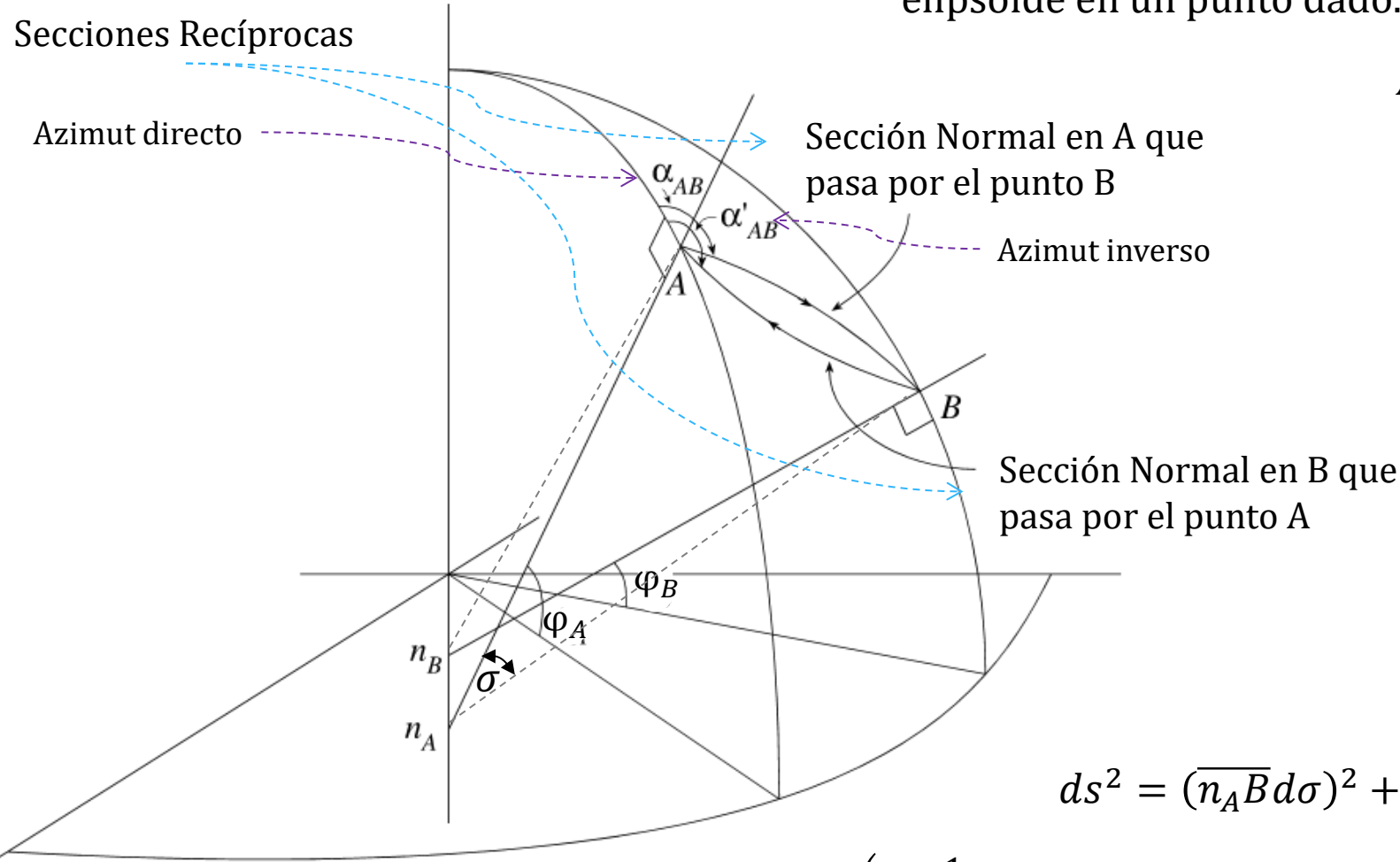
Caso $\varphi_A = 0^\circ$; $\alpha_{AB} = 45^\circ$	
S (km)	Δ (")
200	0.399
100	0.085
50	0.021

(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.
(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.
(10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service

Geodesia

Secciones en el elipsoide^(7,9,10):

Sección Normal (definición matemática): curva formada por la intersección de un plano que contiene a la normal a la superficie del elipsoide en un punto dado.



$$ds^2 = (\overline{n_A B} d\sigma)^2 + (d\overline{n_A B})^2$$

$$S_{AB} = N_A \sigma \left(1 + \frac{1}{6} \sigma^2 \eta_A^2 \cos^2 \alpha_{AB} (\eta_A^2 \cos^2 \alpha_{AB} - 1) + \frac{1}{8} t_A \eta_A^2 \cos \alpha_{AB} (1 - 3 \eta_A^2 \cos^2 \alpha_{AB}) \sigma^3 \right)$$

Fuente: Jekeli, C. (2006)

(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

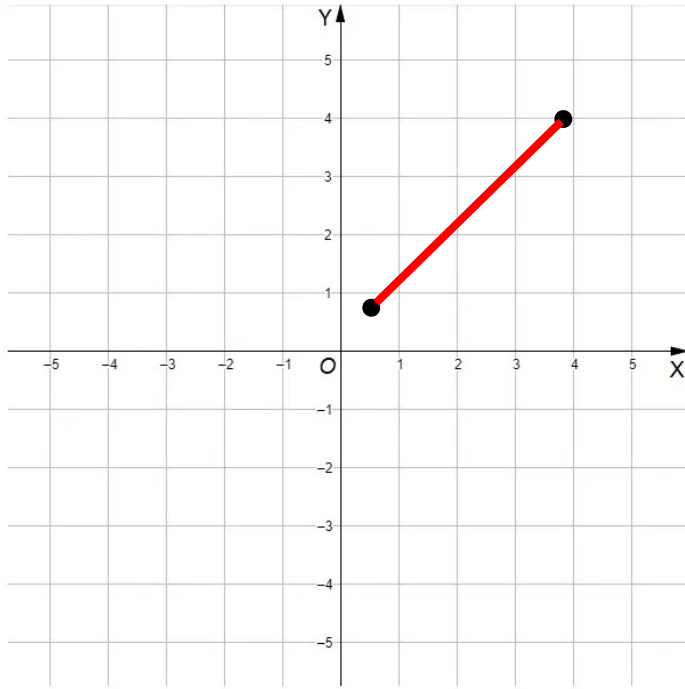
(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.

(10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service

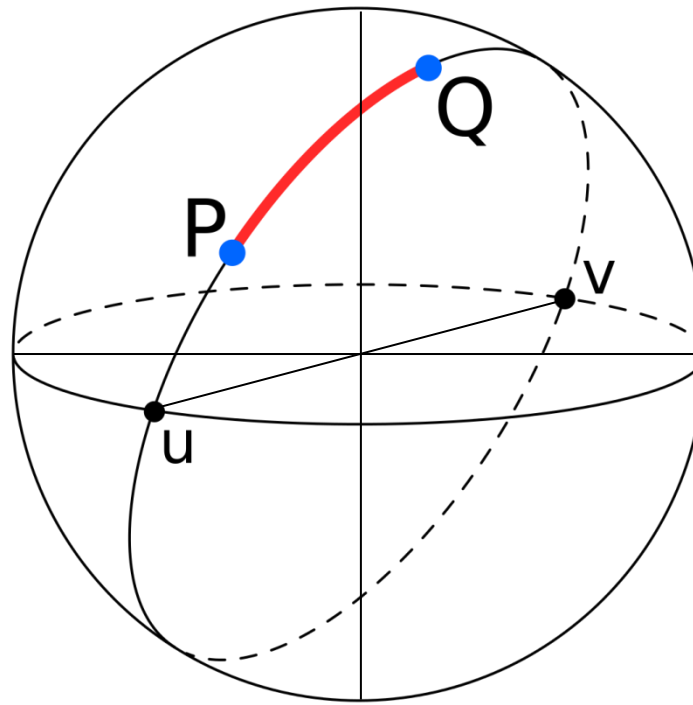
Geodesia

Geodésicas^(7,9,10): Longitud más corta entre dos puntos sobre una superficie.

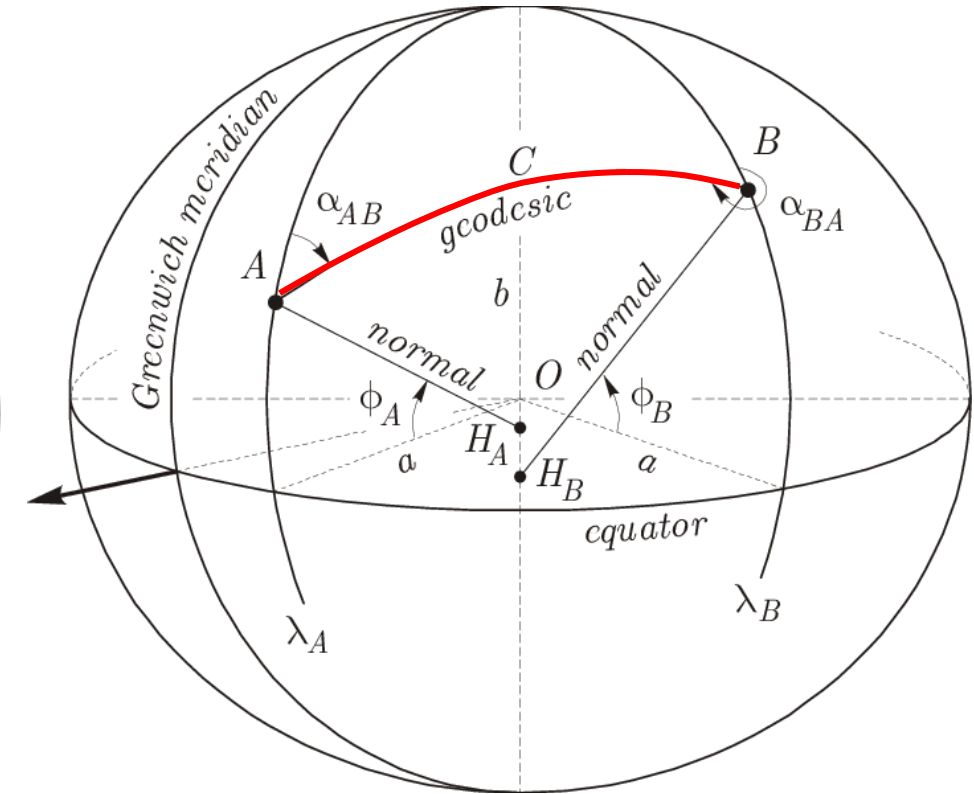
Geodésica en el plano



Geodésica en la esfera



Geodésica en el elipsoide



Fuente: Deakin, R. E., (2005).

Traverse computation: Ellipsoid versus the UTM projection.

(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

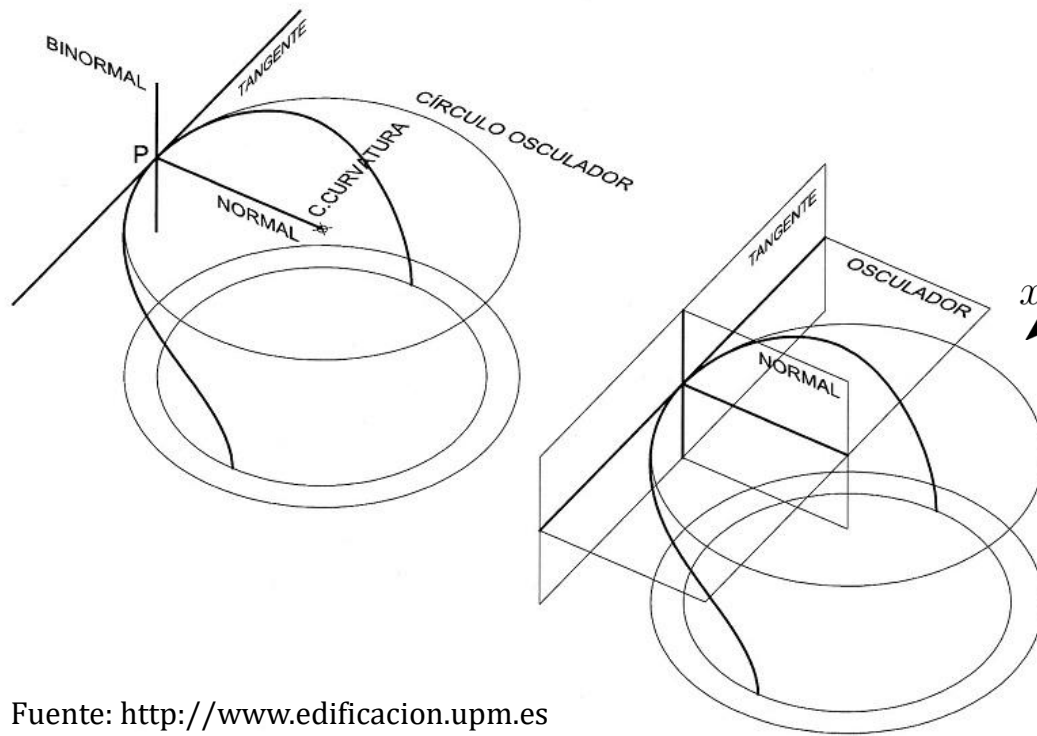
(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.

(10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service

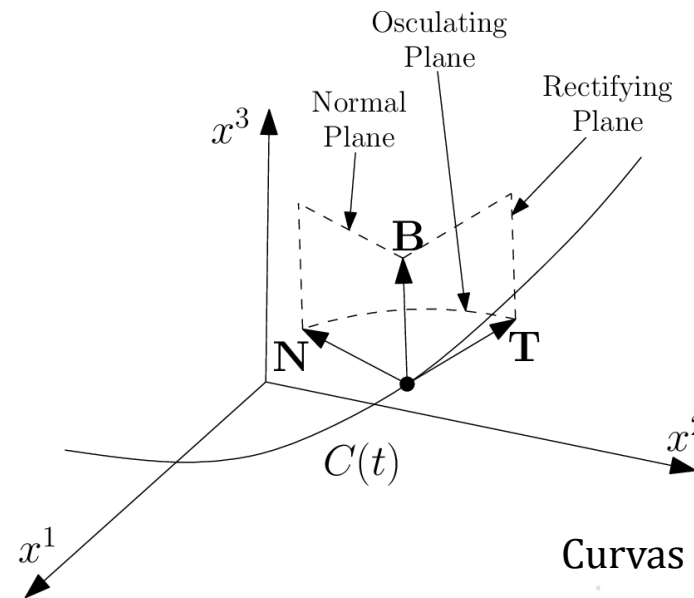
Geodesia

Geodésicas^(7,9,10): toda curva sobre una superficie cuyo plano osculador contiene a la normal a la superficie en cualquier punto.

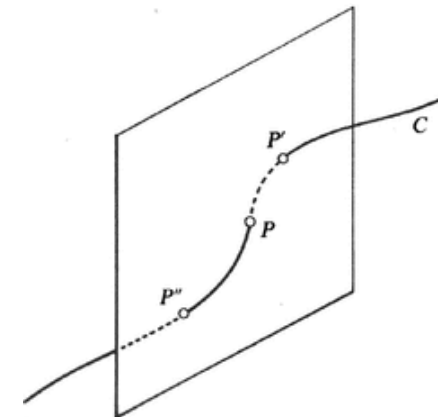
Triedo de Frenet



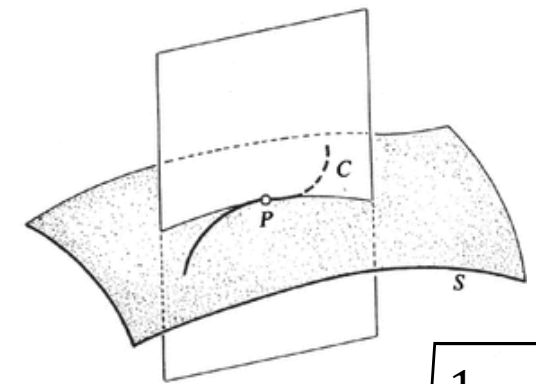
Fuente: <http://www.edificacion.upm.es>



Curvas planas



Doble curvatura

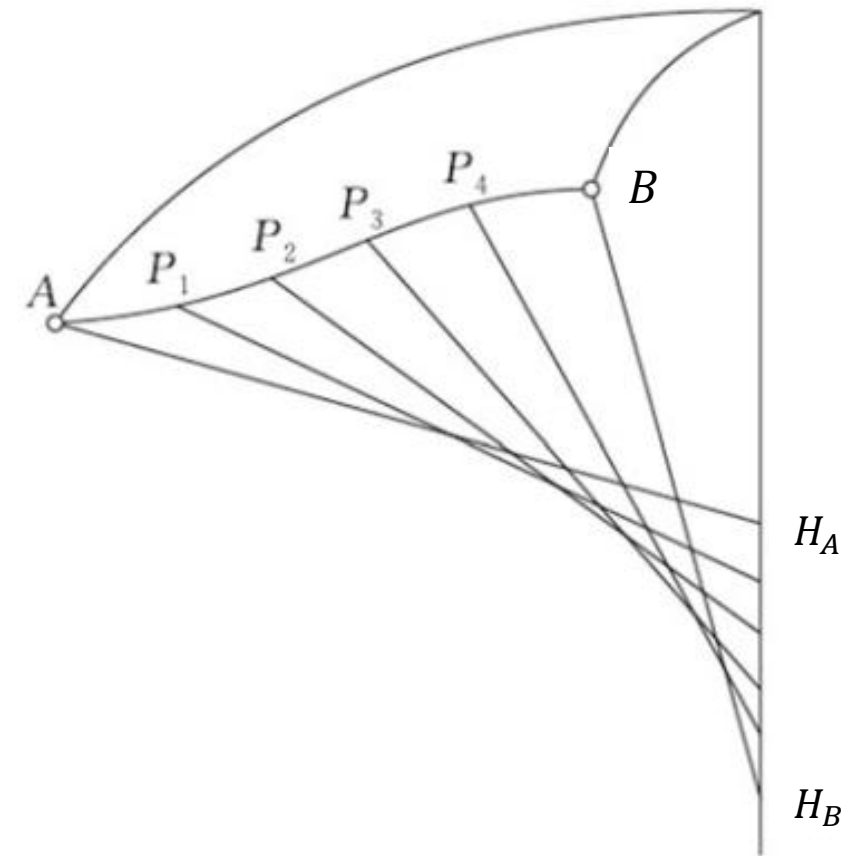
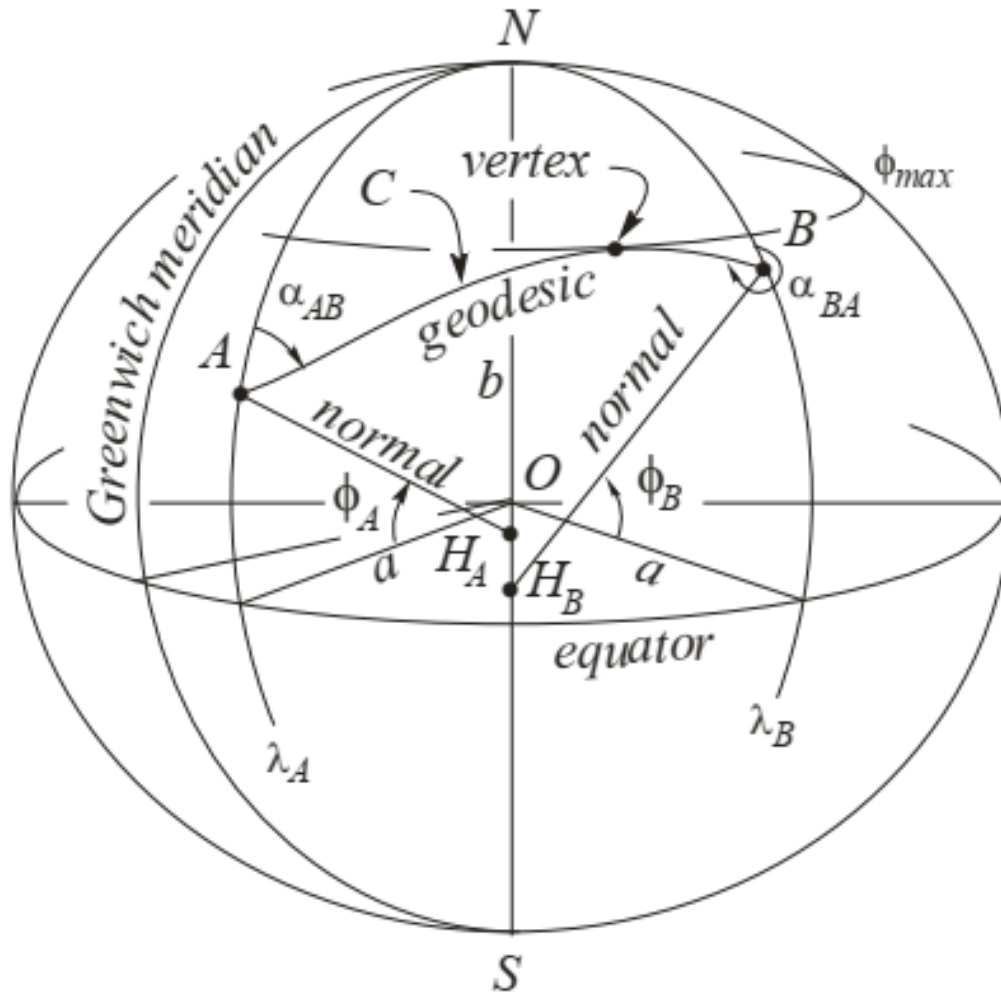


$$\sqrt{\frac{1}{\chi^2} + \frac{1}{\tau^2}}$$

Fuente: <http://faculty.etsu.edu>

Geodesia

Geodésicas^(7,9,10): toda curva sobre una superficie cuyo plano osculador contiene a la normal a la superficie en cualquier punto.



Fuente: Deakin, R. E., & Hunter, M. N. (2009).

Fuente: Lu Z., Qu Y., Qiao S. (2014)

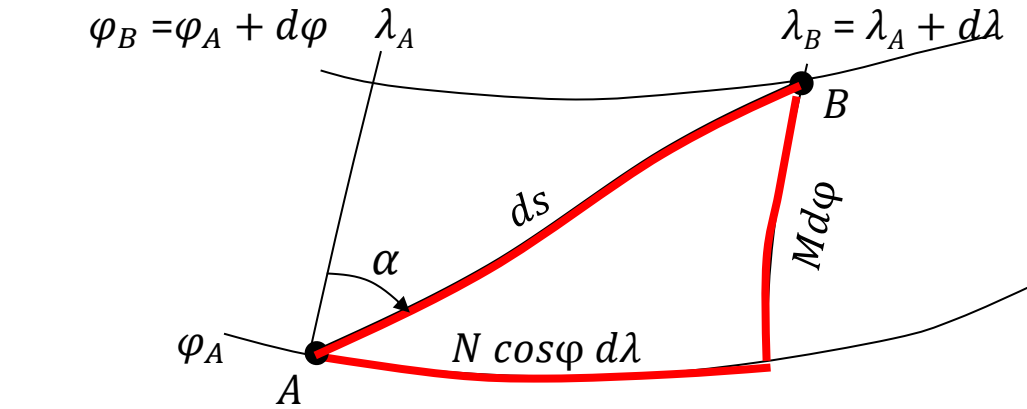
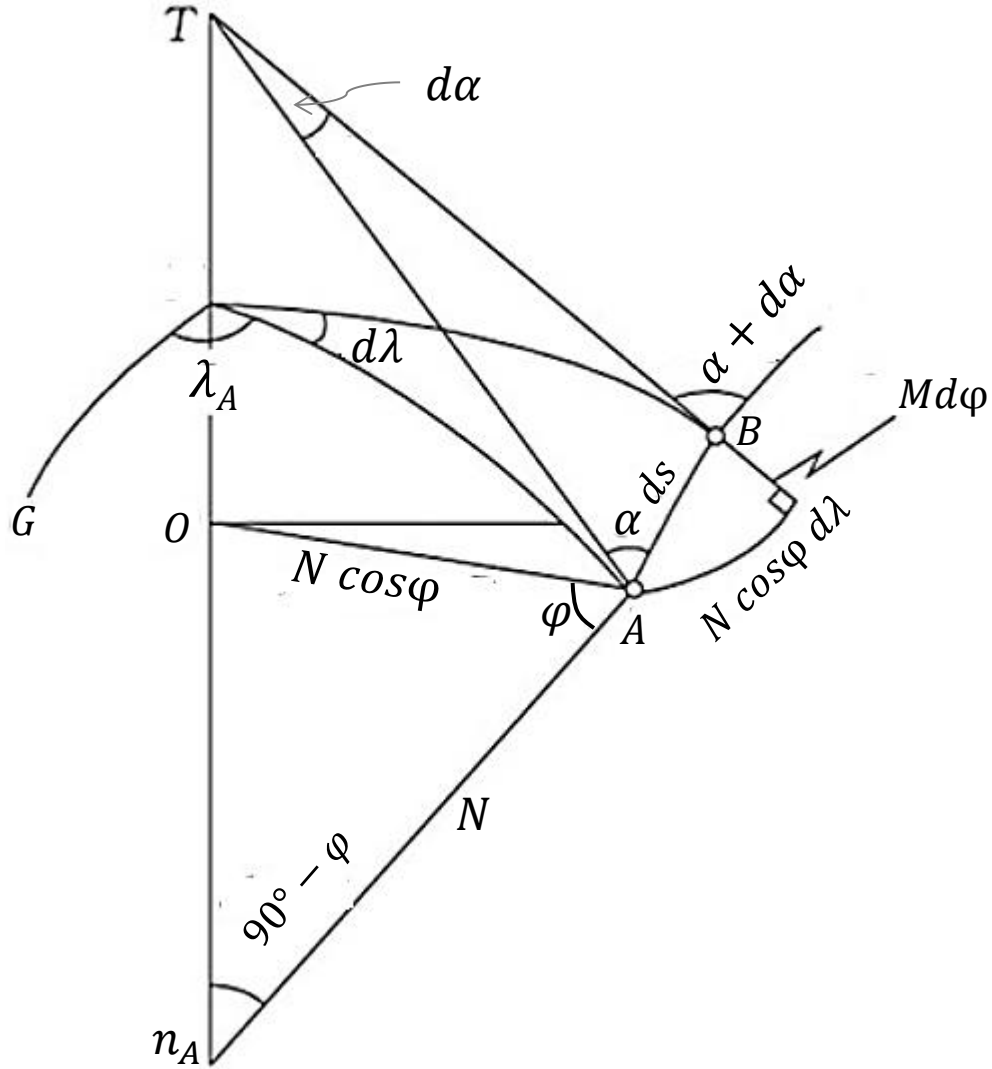
(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.

(10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service

Geodesia

Ecuación Fundamental de la Geodésica^(7,9,10):



$$\cos \alpha = \frac{Md\varphi}{dS} \rightarrow dS \cos \alpha = Md\varphi$$

$$\text{sen } \alpha = \frac{N \cos \varphi \, d\lambda}{dS} \rightarrow dS \text{ sen } \alpha = N \cos \varphi \, d\lambda$$

$$d\alpha = \frac{N \cos\varphi \, d\lambda}{AT}$$

$$\cos(90^\circ - \varphi) = \frac{N \cos \varphi}{AT}$$

$$d\alpha = \underset{\uparrow}{\text{sen } \varphi} d\lambda \rightarrow d\alpha = \frac{\text{sen } \alpha}{N} \text{tg } \varphi dS$$

Ecuación de Laplace

$$dS = \sqrt{(M d\varphi)^2 + (N \cos\varphi d\lambda)^2} \rightarrow I = \int_A^B dS \rightarrow \text{mínima}$$

Fuente: Lu Z., Qu Y., Qiao S. (2014)

(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

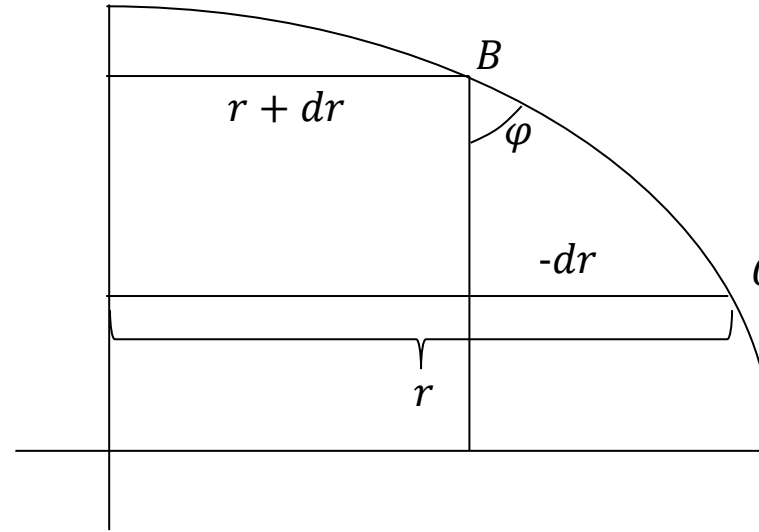
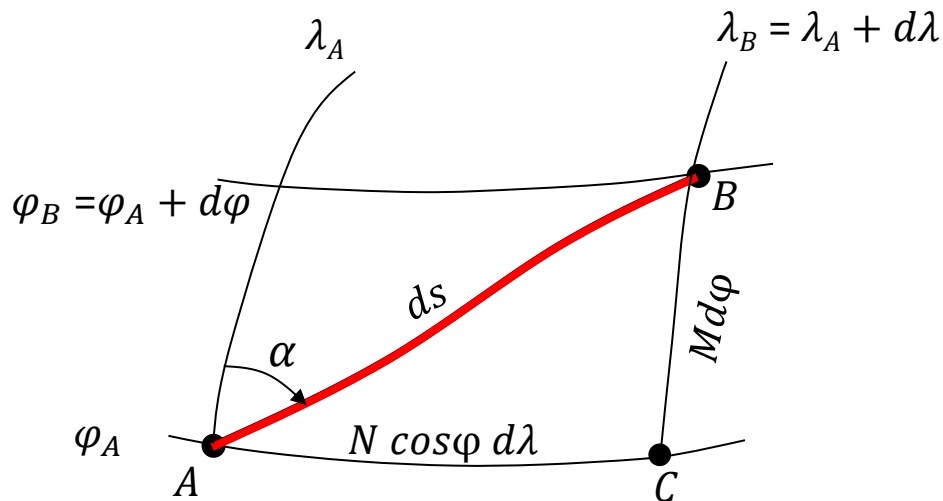
(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.

(10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service

Geodesia

Ecuación Fundamental de la Geodésicas^(7,9,10):

Longitud más corta entre dos puntos sobre una superficie. $\rightarrow I = \int_A^B dS \rightarrow \text{mínima}$



$$-dr = M \operatorname{sen} \varphi d\varphi$$

$$\left. \begin{aligned} dS \cos \alpha &= M d\varphi \\ dS \operatorname{sen} \alpha &= N \cos \varphi d\lambda = r d\lambda \end{aligned} \right\} \begin{aligned} \cos \alpha &= \frac{M d\varphi}{dS} \rightarrow r d\alpha \cos \alpha = \frac{M d\varphi}{dS} r d\alpha = \frac{M d\varphi}{dS} r \operatorname{sen} \varphi d\lambda \\ \operatorname{sen} \alpha &= \frac{N \cos \varphi d\lambda}{dS} \rightarrow dr \operatorname{sen} \alpha = r \frac{d\lambda}{dS} dr = -r \frac{d\lambda}{dS} M \operatorname{sen} \varphi d\varphi \end{aligned} \right\}$$

$$r d\alpha \cos \alpha + dr \operatorname{sen} \alpha = 0$$

$$\downarrow$$

$$r \operatorname{sen} \alpha = cte$$

$$N \cos \varphi \operatorname{sen} \alpha = cte$$

Ecuación de Clairaut

(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

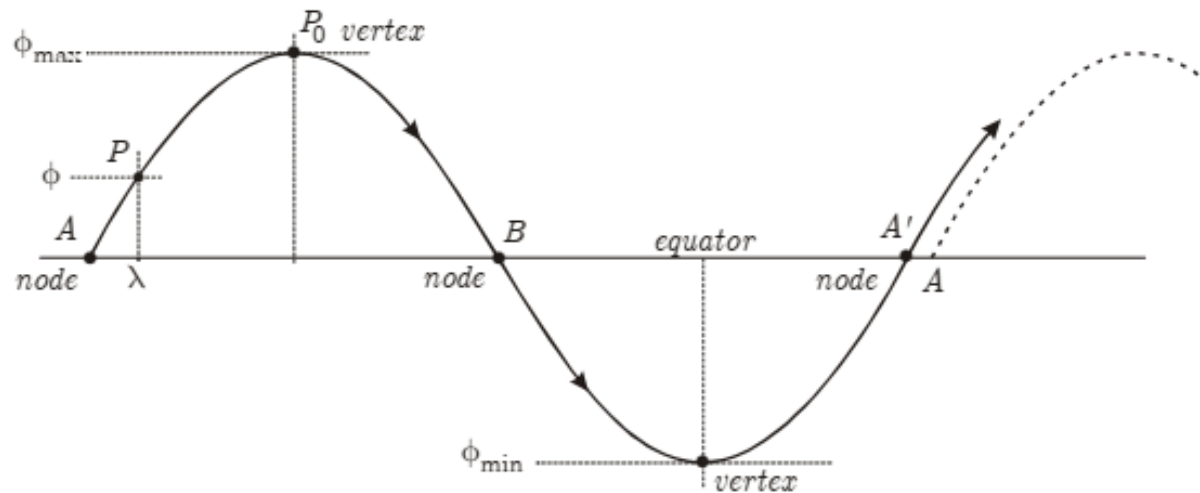
(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.

(10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service

Geodesia

Geodésicas^(7,9,10): Longitud más corta entre dos puntos sobre una superficie.

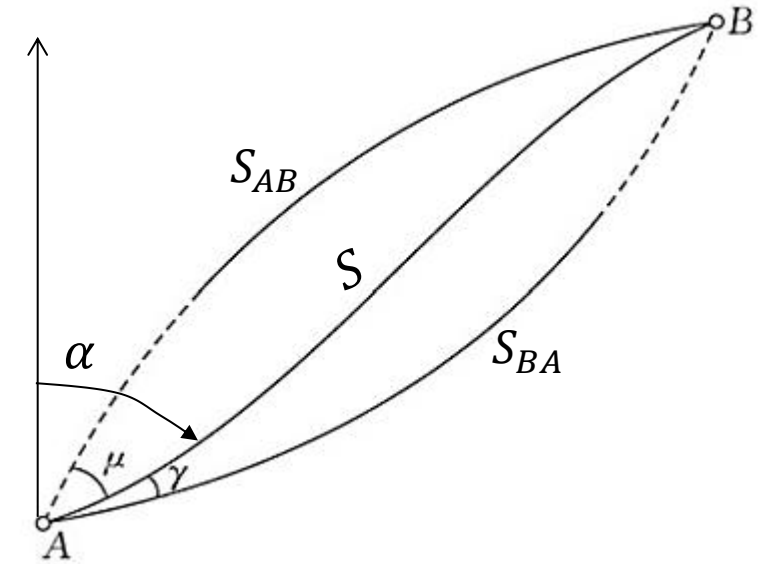
Ecuación de Clairaut $N \cos \varphi \sin \alpha = cte$



$$N \cos \varphi = a \cos \beta$$

$$a \cos \beta \sin \alpha = k$$

$$\text{Si } \beta = 0^\circ \rightarrow \sin \alpha_E = \frac{k}{a}$$



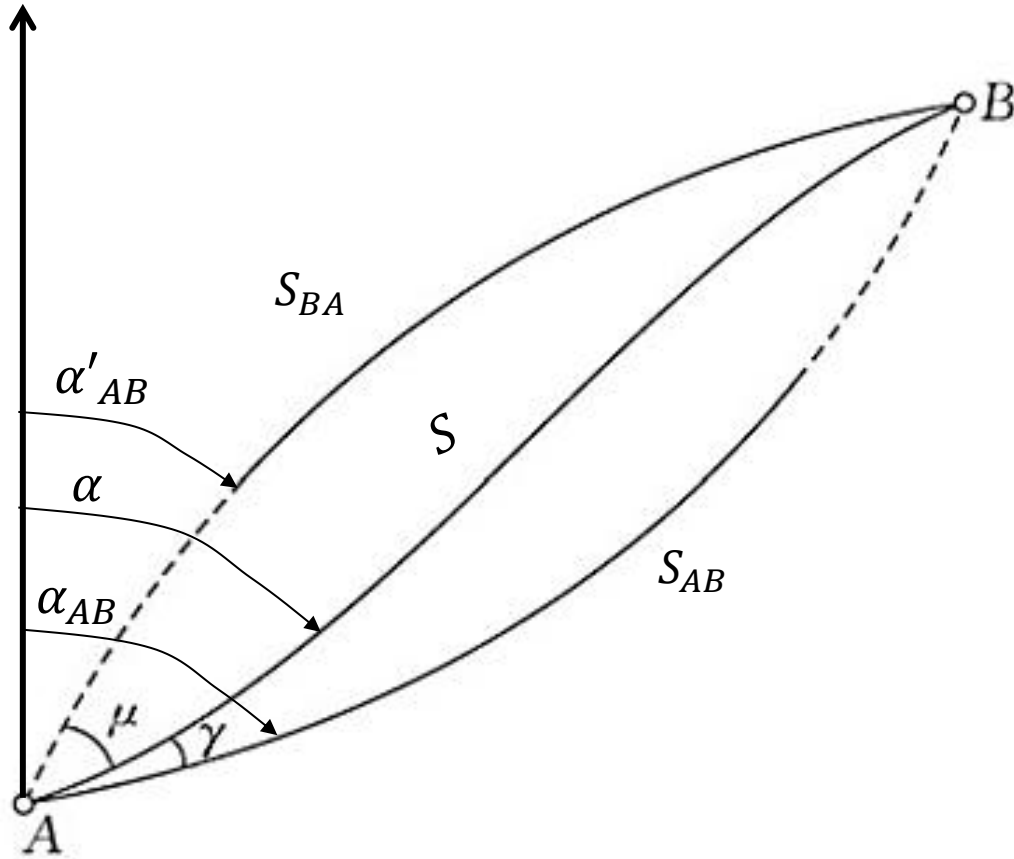
Fuente: Lu Z., Qu Y., Qiao S. (2014)

Fuente: Deakin, R. E., & Hunter, M. N. (2009).

- (7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.
 (9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.
 (10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service

Geodesia

Diferencia entre sección normal y Geodésica^(7,9,10):



Diferencia de azimuth entre secciones recíprocas

$$\Delta = \alpha_{AB} - \alpha'_{AB} = \frac{e^2}{4} \left(\frac{S_{AB}}{N_A} \right)^2 \text{sen} 2\alpha_{AB} \cos^2 \varphi_m$$

Diferencia de azimuth entre sección normal y geodésica

$$\gamma = \alpha_{AB} - \alpha = \frac{\eta^2}{2} \left(\frac{S_{AB}}{N_A} \right)^2 \text{sen} \alpha_{AB} \cos \alpha_{AB} + \frac{\eta^2 t}{24} \left(\frac{S_{AB}}{N_A} \right)^3 \text{sen} \alpha_{AB} \cong \frac{\Delta}{3}$$

Diferencia de longitud entre sección normal y geodésica

$$S_{AB} - S = \frac{a e^4}{360} \left(\frac{S_{AB}}{N_A} \right)^5 \text{sen}^2 2\alpha \cos^4 \varphi$$

Fuente: Lu Z., Qu Y., Qiao S. (2014)

(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

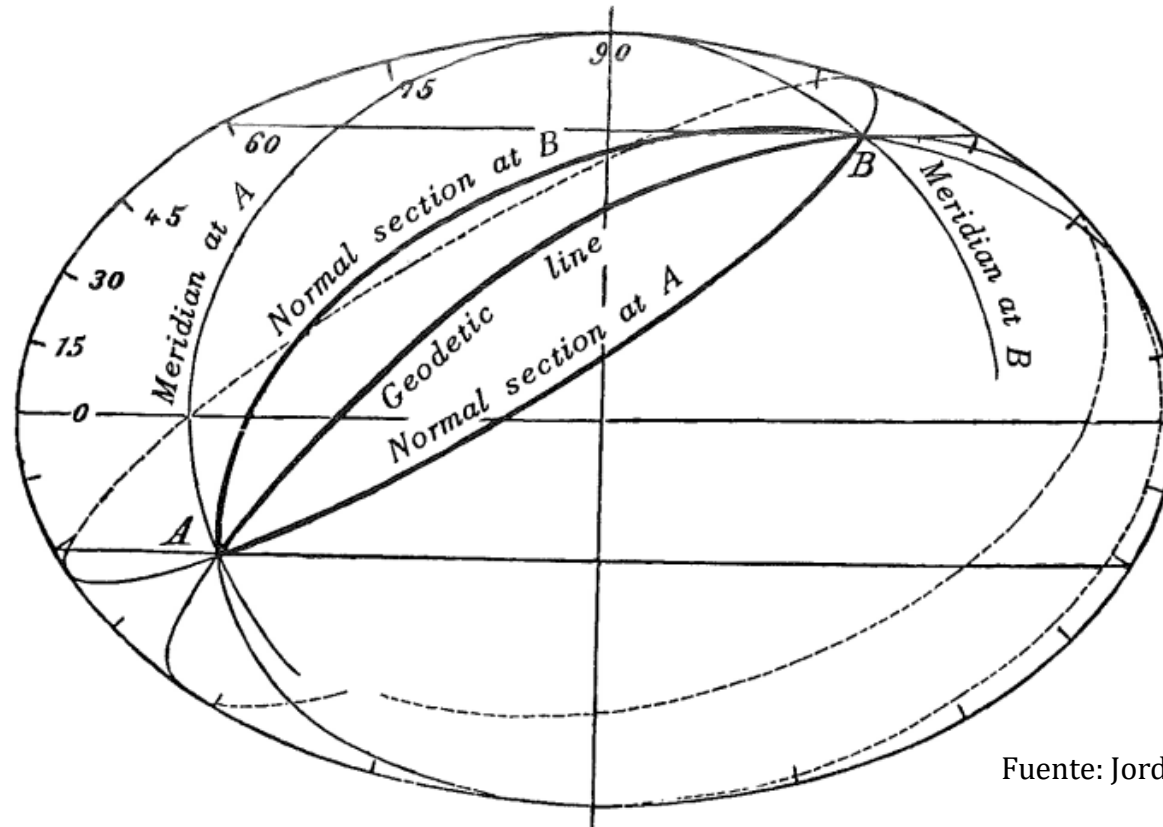
(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.

(10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service

Geodesia

Consecuencias^(7,9,10):

- La normal principal de la geodésica es normal al elipsoide en cada punto de la geodésica;
- Cualquier meridiano es una geodésica;
- El ecuador es una geodésica, excepto para puntos diametralmente opuestos;
- Los círculos paralelos no son geodésicas;
- Una geodésica en el elipsoide es una curva de doble curvatura, excepto dos casos particulares;
- Una geodésica alcanza latitudes máximas y mínimas ($\varphi_{\text{máx}} = -\varphi_{\text{mín}}$);



Fuente: Jordan, W. (1962).

(7) Rapp, Richard H. (1991). *Geometric geodesy part I*. Department of Geodetic Science and Surveying, Ohio State University.

(9) Jekeli, C. (2006). *Geometric reference systems in geodesy*. Division of Geodetic Science, School of Earth Sciences. Ohio State University.

(10) Jordan, W. (1962). *Handbook of Geodesy* (Vol. 3). Corps of Engineers, United States Army, Army Map Service